





Very old

-64°... +42°C

89% humidity

30G vibration

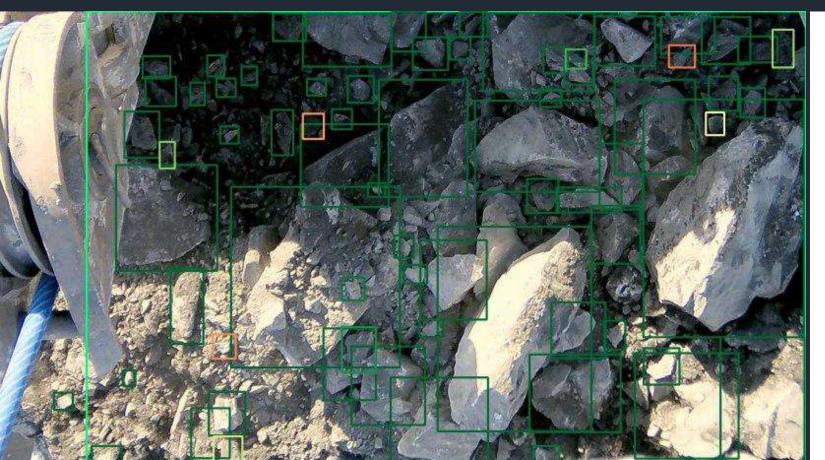
Poor network

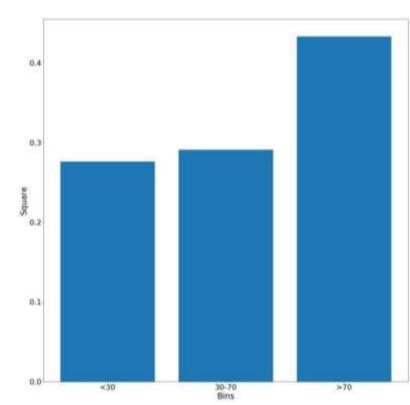
Physical access once a month

Let's do some Al

We measure fragmentation

- The most accurate way it to look at each bucket
- Over 1000 measurements each shift



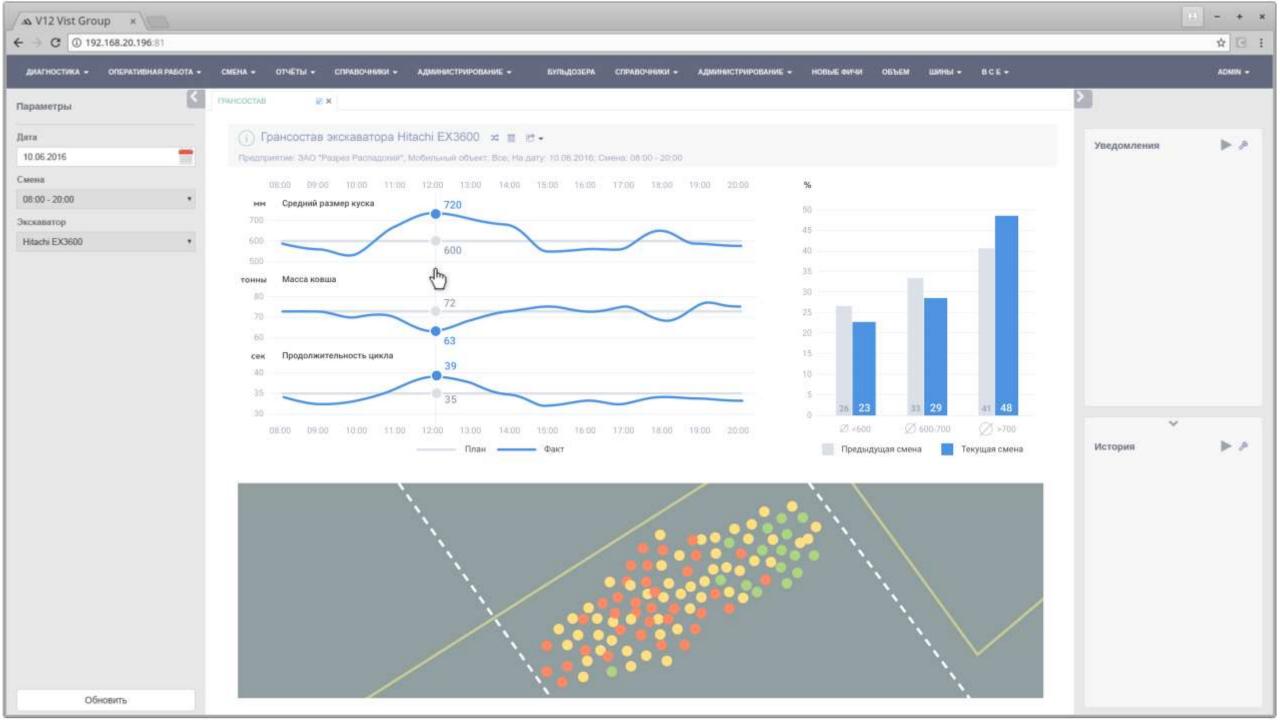


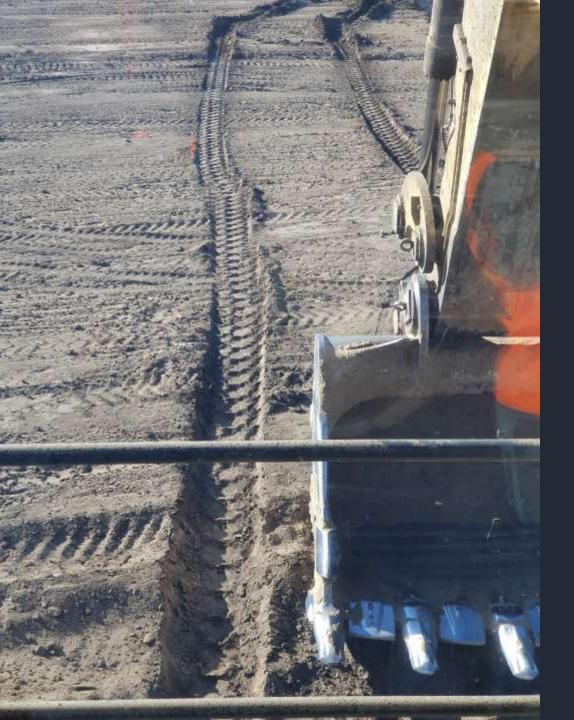
Why do it?

- Too small fragments means overused explosives
- Too large fragments makes it difficult to excavate, transport & crush
- Enables feedback on blasting & drilling job
- Enables mine-to-mill approach

\$M 5-20 effect per mine







We control the teeth

- Picture: what the operator sees
- Instant reaction to the loss
- Alarm to the operator & dispatch
- In any conditions



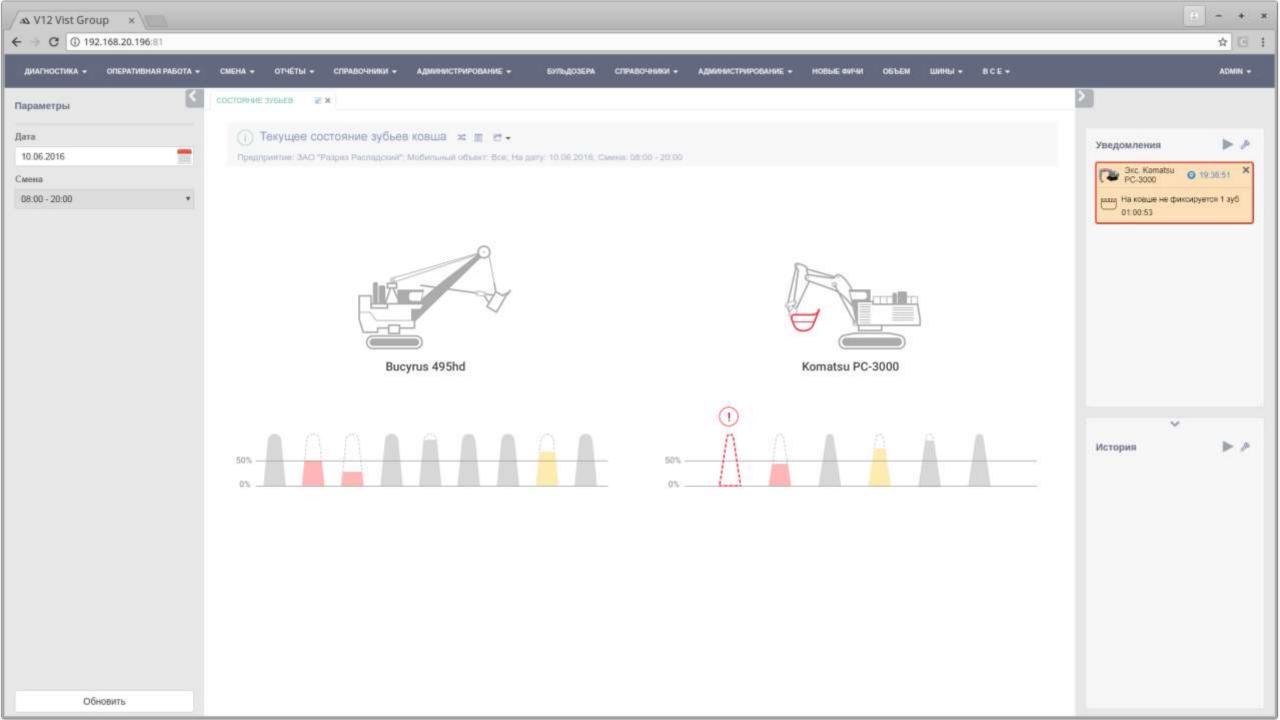


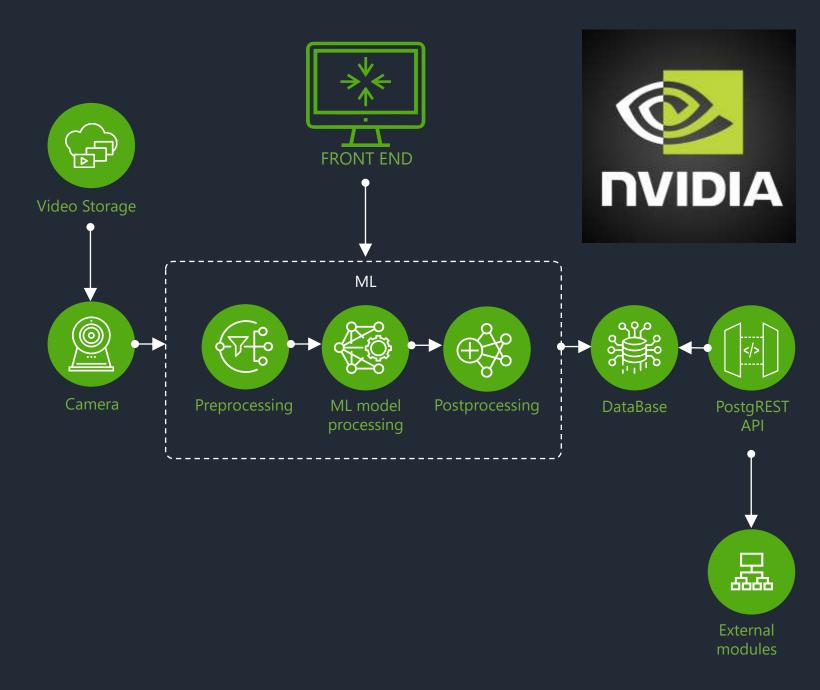
Why do it?

- Tooth loss occurs
 10+ times a year per mine
- Tooth can break the crusher
- This causes at least downtime
- At worst crusher repair

\$K 100-500 savings when crusher incident prevented







What's inside?

- FullHD IP-camera
- NVIDIA Xavier
- Deep Learning
- Real-time inference
- API to any dispatch system

What else?

- Safety control
- Collision prevention
- Fatigue monitoring
- Automatic operations
- Remote control
- Autonomous machines





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Thank you!

